

MAS 863 *How To Make (almost) Anything* 2009

## **Networking and Communications**

During the Thanksgiving and this week, I did two things. One is making a network and the other is reviewing what I learned for this semester so far.

For the network, I made an IO, a serial and a hub board. After writing a program into three boards, I connected serial board and computer. It looks good and I succeeded to get a THTP address of http://15.85.47.95:1111/. However, when I clicked the button, I could not get a random address as I heard from the demo last class.



The second, actually major, thing I did was reviewing the class. Though I made lots of boards and sensors, and I made them all works, I felt like that I was not confident about what I am doing.

Since I need to work at my lab most of the time, I made breadboard prototypes with ATtiny series (t13, t45, t44a, mega88 and mega168 from Arduino).



Review of PCB Fabrication Week

I remade a board with ATTiny13 from a scratch. All the codes were written in C programming language.



Review of Input Devices - ADC

This board uses light sensor. When the value of a light sensor exceeds 128 (a median value of ADC, a LED turns on)



Review of Input Devices – ADC Distance Sensor PWM

In this example, the distance sensor sends the distance value using ADC, brightness of light is changed based on the received value.



Earthquate Sensing and Simulation using Accelerometer



## Earthquake Richter Scale 4 : Warning

Received Data: 419

🛃 Start	arduino-0017	arduino-0017	acceleromet	sketch_dec	🛃 accel_arduin	SCOM7	🖳 Form1	2	99%		« 🗐 🔊)	5:41 AM
---------	--------------	--------------	-------------	------------	----------------	-------	---------	---	-----	--	--------	---------

## Review of Output Devices – UART

Serial Communication For the lab project, I used a accelerometer with C# simulation. A received date from the accelerometer communicates with C# using a serial port. Based on the received data, the degree of screen shakes varies. I used Arduino for this project since I did not fully understand the UART in Attiny yet.