

(b) Matrix coeffs For linear hat basis functions of fixed size h:

$$\phi_i = \begin{cases} \frac{x - x_{i-1}}{x_i - x_{i-1}}, & x_{i-1} \leq x < x_i = \frac{x - x_{i-1}}{h} \\ \frac{x_{i+1} - x}{x_{i+1} - x_i}, & x_i \leq x < x_{i+1} = \frac{x_i + h - x}{h} \end{cases}$$

$$A_{ij} = \int \phi_i \phi_j dx = \int_{x_{i-h}}^{x_i} \left(\frac{x - (x_i - h)}{h} \right)^2 dx + \int_{x_i}^{x_{i+h}} \left(\frac{(x_i + h) - x}{h} \right)^2 dx$$

$$= \int_{x_{i-h}}^{x_i} \frac{x^2 - 2x(x_i - h) + (x_i - h)^2}{h^2} dx + \int_{x_i}^{x_{i+h}} \frac{x_i^2 + 2x_i h - 2x + h^2}{h^2} dx$$

$$= \frac{1}{h^2} \left[x^3 (x_i - h) - x(x_i - h)^2 + \frac{(x_i - h)^3}{3} \right]_{x_{i-h}}^{x_i}$$

$$+ \frac{1}{h^2} \left[\frac{x_i^3}{3} + x_i^2 h + x_i^2 x - x h x_i^2 + h^2 x_i + x^2 x_i \right]_{x_i}^{x_{i+h}}$$

$$= \frac{1}{h^2} \left(x^3 (x_i - h) - x(x_i - h)^2 + \frac{(x_i - h)^3}{3} \right)$$

$$+ \frac{x_i^3 - (x_i + h)^3}{3} + h(x_i^2 - (x_i + h)^2) - x(x_i^2 - (x_i + h)^2)$$

$$- x h (x_i^2 - (x_i + h)^2) + h^2 (x_i^2 - (x_i + h)^2)$$

$$+ x^2 (x_i - (x_i + h))$$

$$\begin{aligned}
&= \frac{1}{h^2} \left[-hx^2 - x \left(\cancel{x_i} - 2hx_i + h^2 - \cancel{x_i^2} \right) + \frac{1}{3} \left(\cancel{x_i^3} - 2\cancel{x_i^2}h + \cancel{x_i}h^2 - \cancel{hx_i^2} - 2\cancel{x_i}h^2 - \cancel{h^3} \right) \right. \\
&\quad \left. - \frac{\cancel{x_i^3}}{3} \right] \\
&+ \frac{1}{h^2} \left[\frac{x_i^3}{3} + \frac{1}{3} \left(\cancel{x_i^3} + 2\cancel{x_i}h - \cancel{x_i}h^2 + \cancel{hx_i^2} + 2\cancel{x_i}h^2 + \cancel{h^3} \right) \right. \\
&\quad + hx_i^2 - x_i^2h + 2x_ih^2 + h^3 - x \left(x_i^2 - x_i^2 + 2x_ih + h^2 \right) \\
&\quad - xh \left(x_i^2 \left(x_i^2 + 2x_ih + h^2 \right) \right) \\
&\quad + h^2x_i^2 - h^2 \left(x_i^2 + 2x_ih + h^2 \right) \\
&\quad \left. + x^2x_i - x^2 \left(x_i^2 + 2x_ih + h^2 \right) \right]
\end{aligned}$$

$$A_{ij} = \frac{2h}{3}$$

$$\begin{aligned}
B_{ij} &= \int \frac{d^2 \phi_i}{dx^2} \phi_j(x) dx \\
&= \int_{x_{i-h}}^{x_i} \frac{1}{h^2} dx + \int_{x_i}^{x_i+h} \frac{1}{h^2} dx
\end{aligned}$$

$$B_{ij} = \frac{2}{h}$$

(c) see code (matlab)

9.2 see code (matlab)