

(9.1)

$$\frac{\partial^2 u}{\partial t^2} = v^2 \frac{\partial^2 u}{\partial x^2} + \gamma \frac{d}{dt} \frac{\partial^2 u}{\partial x^2}$$

solution domain $[0, 1]$

A. Galerkin method to find approximating system of diff eqs

$$R(\vec{x}, t) = D[\hat{u}(\vec{x}, t)] - f(\vec{x}, t)$$

$$u(\vec{x}, t) \approx \sum_i a_i(t) \varphi_i(\vec{x})$$

$$\int R(\vec{x}) w_i(\vec{x}) d\vec{x} = 0 \quad w_i(\vec{x}) = \varphi_i(\vec{x})$$

$$\int \left(\frac{\partial^2 u}{\partial t^2} - v^2 \frac{\partial^2 u}{\partial x^2} - \gamma \frac{d}{dt} \frac{\partial^2 u}{\partial x^2} \right) \varphi_j dx = 0$$

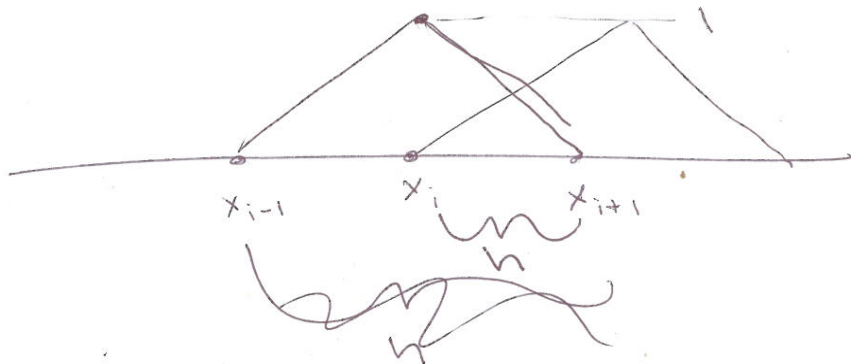
$$\rightarrow \sum_i \int \left(\frac{d^2 a_i}{dt^2} \varphi_i - v^2 a_i \frac{d^2 \varphi_i}{dx^2} - \gamma \frac{da_i}{dt} \frac{d^2 \varphi_i}{dx^2} \right) \varphi_j dx = 0$$

$$= A \frac{d^2 a_i}{dt^2} - v^2 B a_i - \gamma B \frac{da_i}{dt} = 0$$

$$A_{ij} = \int \varphi_i \varphi_j dx$$

$$B_{ij} = \int \varphi_j \frac{d^2 \varphi_i}{dx^2} dx$$

B. Eval matrix coefficients for linear hat basis function, using elements of fixed size of h



$$\varphi_i = \begin{cases} (x - x_{i-1}) / (x_i - x_{i-1}) & x_{i-1} \leq x \leq x_i \\ x_{i+1} - x / (x_{i+1} - x_i) & x_i \leq x \leq x_{i+1} \\ 0 & x < x_{i-1} \quad \parallel \quad x \geq x_{i+1} \end{cases}$$

if $i=j$ $A_{ij} = \int \varphi_i^2 dx$

$$= \int_{x_{i-1}}^0 \left(\frac{x - x_{i-1}}{h} \right)^2 dx + \int_0^{x_{i+1}} \left(\frac{x_{i+1} - x}{h} \right)^2 dx$$

$$= 2 \int_0^h \left(\frac{h-x}{h} \right)^2 dx$$

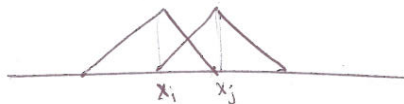
$$= 2 \int_0^h \left(1 - \frac{x}{h} \right)^2 dx$$

$$= 2 \left(\frac{x^3}{3h^2} - \frac{x^2}{h} + x \right) \Big|_0^h$$

← help from wolfram alpha

$$A_{ij} = \frac{2h}{3}$$

if $i = j \pm 1$:



$$\varphi_j = (x - x_i) / (x_j - x_i)$$

$$\varphi_i = (x_j - x) / (x_j - x_i)$$

$$x_i \leq x \leq x_j$$

$$A_{ij} = \int_{x_i}^{x_j} \frac{(x - x_i)}{(x_j - x_i)} \frac{(x_j - x)}{(x_j - x_i)} dx$$

$$= \frac{1}{h^2} \int_0^h (x - 0) (h - x) dx$$

let $x_i = 0$
 $x_j = h$

$$= \frac{1}{h^2} \int_0^h (hx - x^2) dx$$

$$= \frac{1}{h^2} \left(hx^2/2 - x^3/3 \right) \Big|_0^h$$

$$A_{ij} = \frac{h}{6}$$



all other $A_{ij} = 0$

* except boundaries:



$$A_{ij} \Big|_{i=j=0} \parallel i=j=n$$

$$= \left(\frac{h}{3} \right) \frac{1}{2} = \frac{h}{6}$$

for B_{ij} :

$$\frac{\partial^2 \varphi_i}{\partial x^2} = 0 \text{ for all } x$$

so all $B_{ij} = 0$

c. Find matrix coefficients for Hermite polynomial interpolation basis functions elements of fixed size h 1D cubic polynomial

$$u = a_0 + a_1 x + a_2 x^2 + a_3 x^3$$

$$\begin{bmatrix} u_0 \\ \dot{u}_0 \\ u_n \\ \dot{u}_n \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & h & h^2 & h^3 \\ 0 & 1 & 2h & 3h^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

invert

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -3/h^2 & -2/h & 3/h^2 - 1/h \\ 2/h^3 & 1/h^2 & -2/h^3 & 1/h^2 \end{bmatrix}$$

$$\frac{1}{4} (1 - \xi)^2 (2 + \xi)$$

$$\frac{1}{4} (1 + \xi)^2 (2 - \xi)$$

$$a_0 = u_0$$

$$a_1 = \dot{u}_0$$

$$a_2 = u_0 + h\dot{u}_0 + h^2 u_n + h^3 \dot{u}_n$$

$$a_3 = \dot{u}_0 + 2h u_n + 3h^2 \dot{u}_n$$

denom wrt x

9.2 Hermite polynomial shape functions to numerically solve the beam bending equation.

fix disp + slope @ one end

$$V = \int_0^L \left(\frac{1}{2} EI \left(\frac{d^2 u}{dx^2} \right)^2 - u(x) f(x) \right) dx$$

equilibrium given by $dV=0$

$$u(x, t) = \sum_i a_i(t) \varphi_i(x)$$

$$V = \int_0^L \left(\frac{1}{2} EI \left(\sum_i a_i(t) \frac{d^2 \varphi_i}{dx^2} \right)^2 - \sum_i a_i(t) \varphi_i(x) f(x) \right) dx$$

$$\frac{\partial V}{\partial a_j} = 0$$

$$0 = \frac{d}{da_j} \left(\right)$$

$$= \int_0^L \left(\frac{1}{2} EI \sum_i a_i \left(\frac{d^2 \varphi_i}{dx^2} \frac{d^2 \varphi_j}{dx^2} \right) - \varphi_j f(x) \right) dx$$

$$= \sum_i a_i \int_0^L \frac{1}{2} EI \left(\frac{d^2 \varphi_i}{dx^2} \frac{d^2 \varphi_j}{dx^2} \right) dx - \int_0^L \varphi_j f(x) dx$$

$$A_{ij} = \int_0^L EI \frac{d^2 \varphi_i}{dx^2} \frac{d^2 \varphi_j}{dx^2} dx$$

$$\vec{B}_j = \int_0^L \varphi_j(x) f(x) dx$$

$$A \cdot \vec{a} = \vec{B}$$