



Cornell University



Fab @Home



The Personal
Desktop
Fabricator Kit

Evan Malone, Hod Lipson, Max
Lobovsky, Dan Periard, Jennifer
Yao, etc.

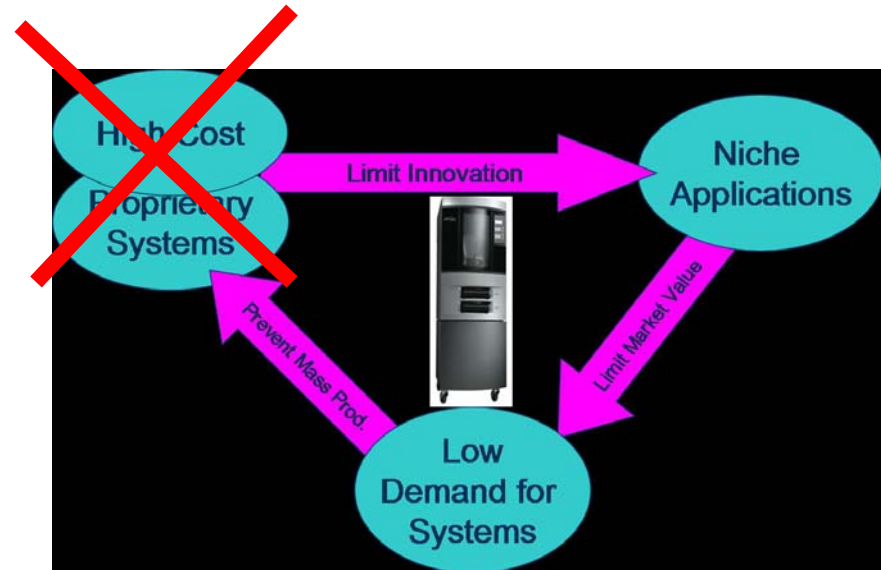
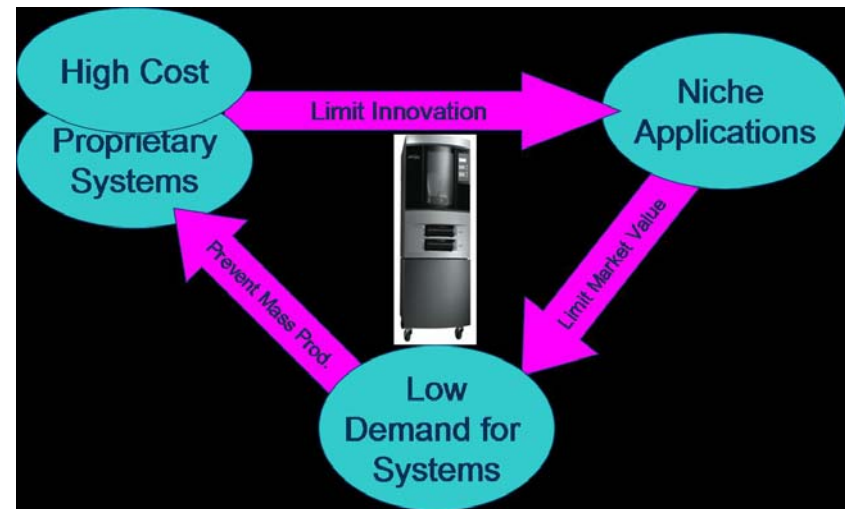
The Fab@Home Project

The Challenge:

How to break SFF/RP free of the high-cost/niche application trap, and help to realize the potential of personal fabrication?

The Fab@Home Response:

Put cheap, open-architecture “fabbers” into the hands of hobbyists and hackers, and let them improve the technology and invent applications!

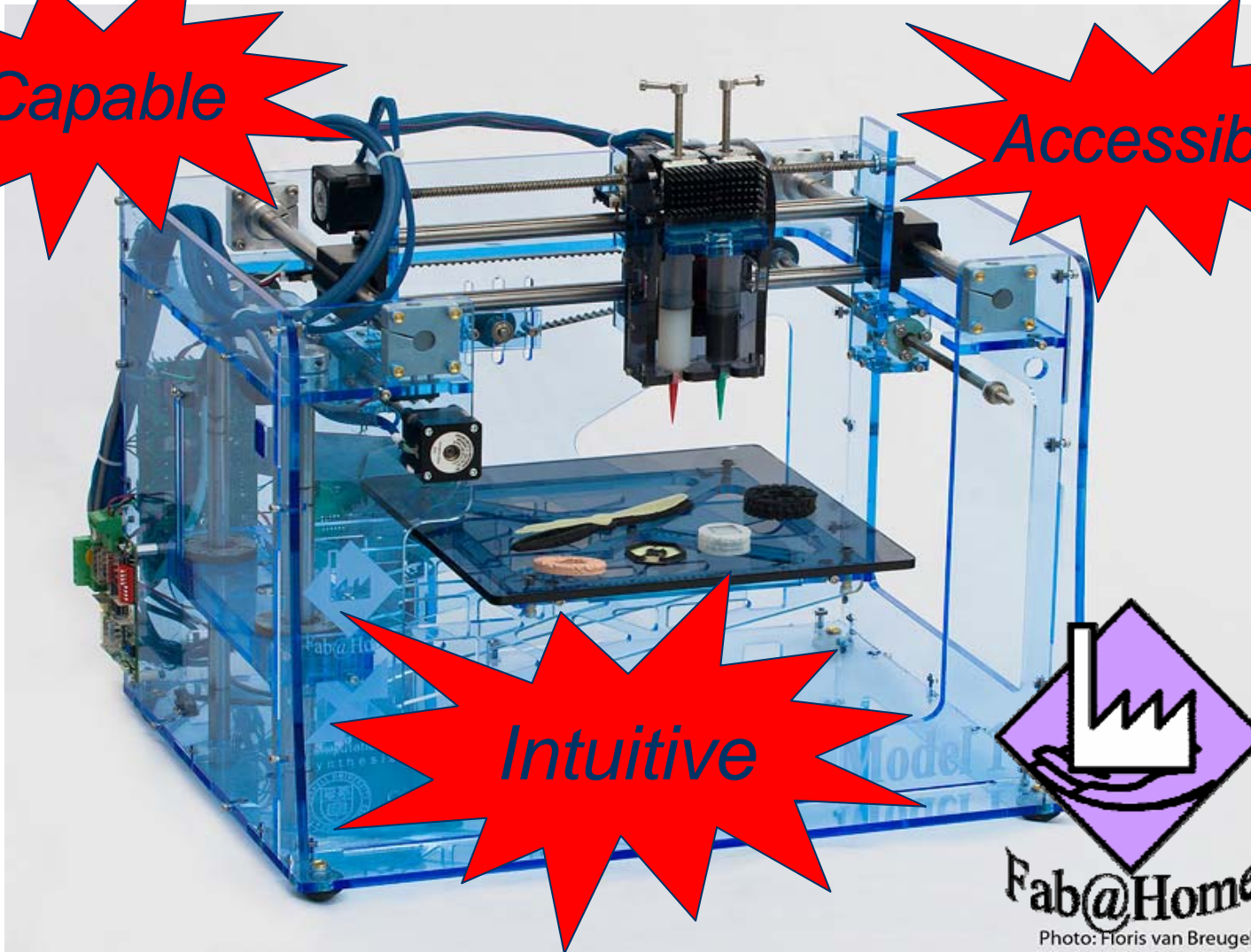


Philosophy

Capable

Accessible

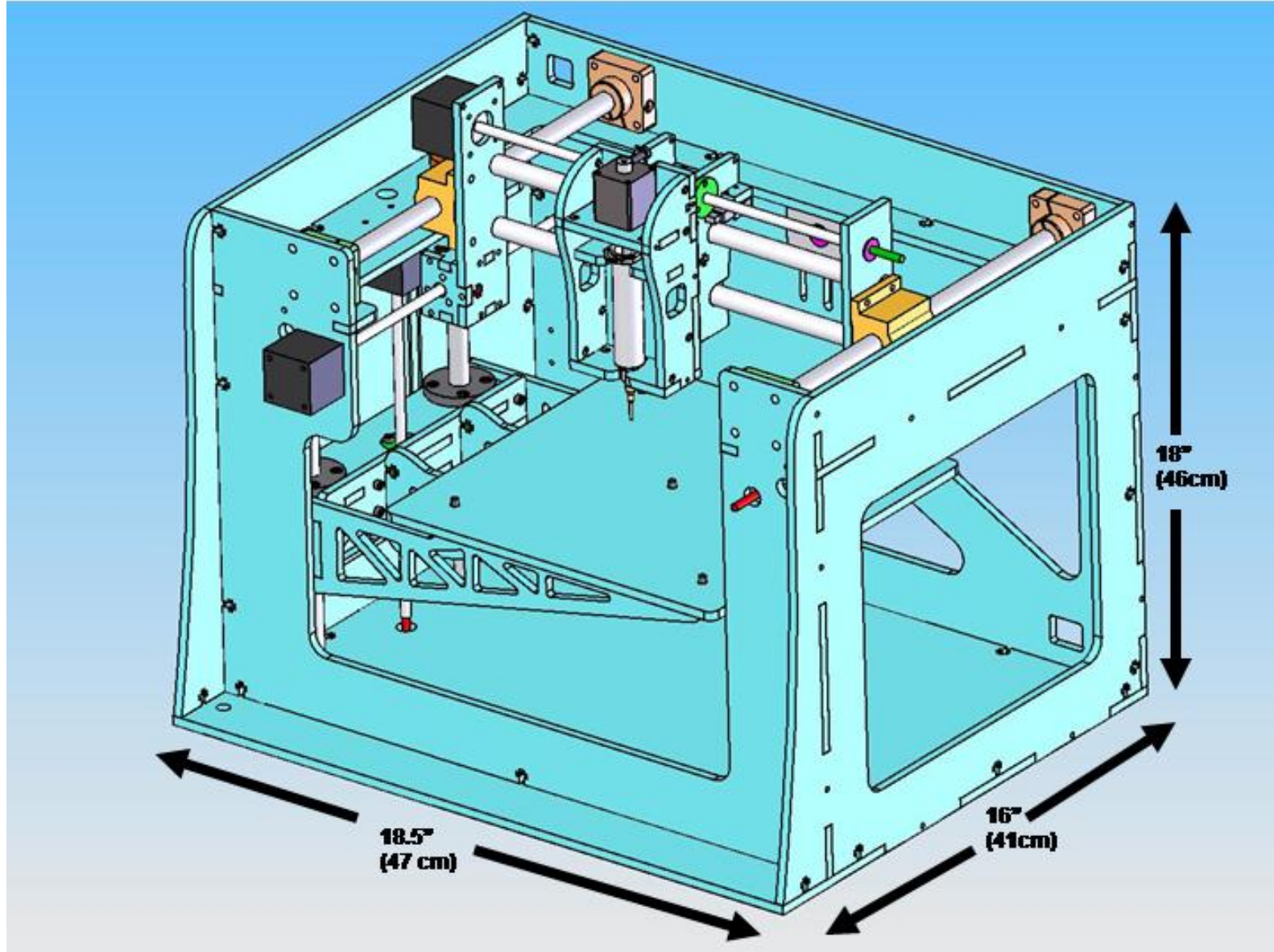
Intuitive



Fab@Home

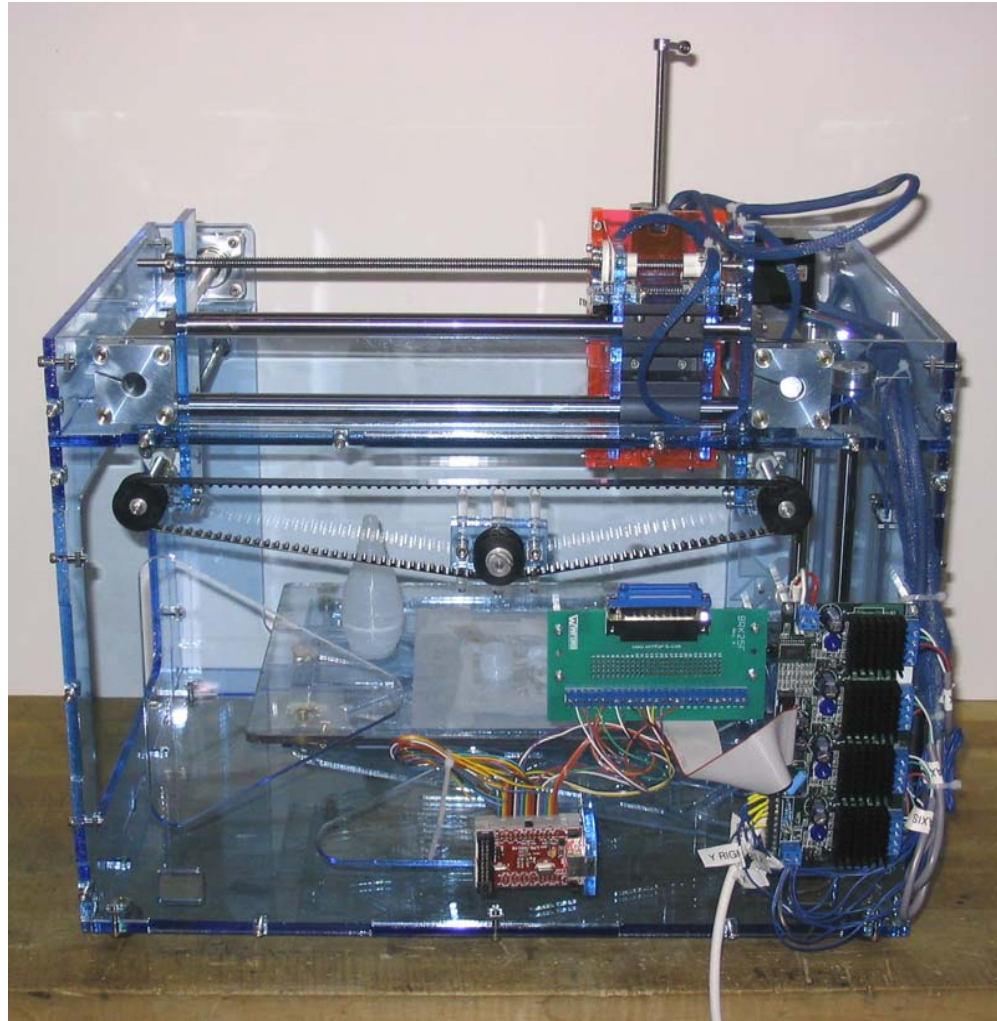
Photo: Floris van Breugel

Technical Details - Mechanical



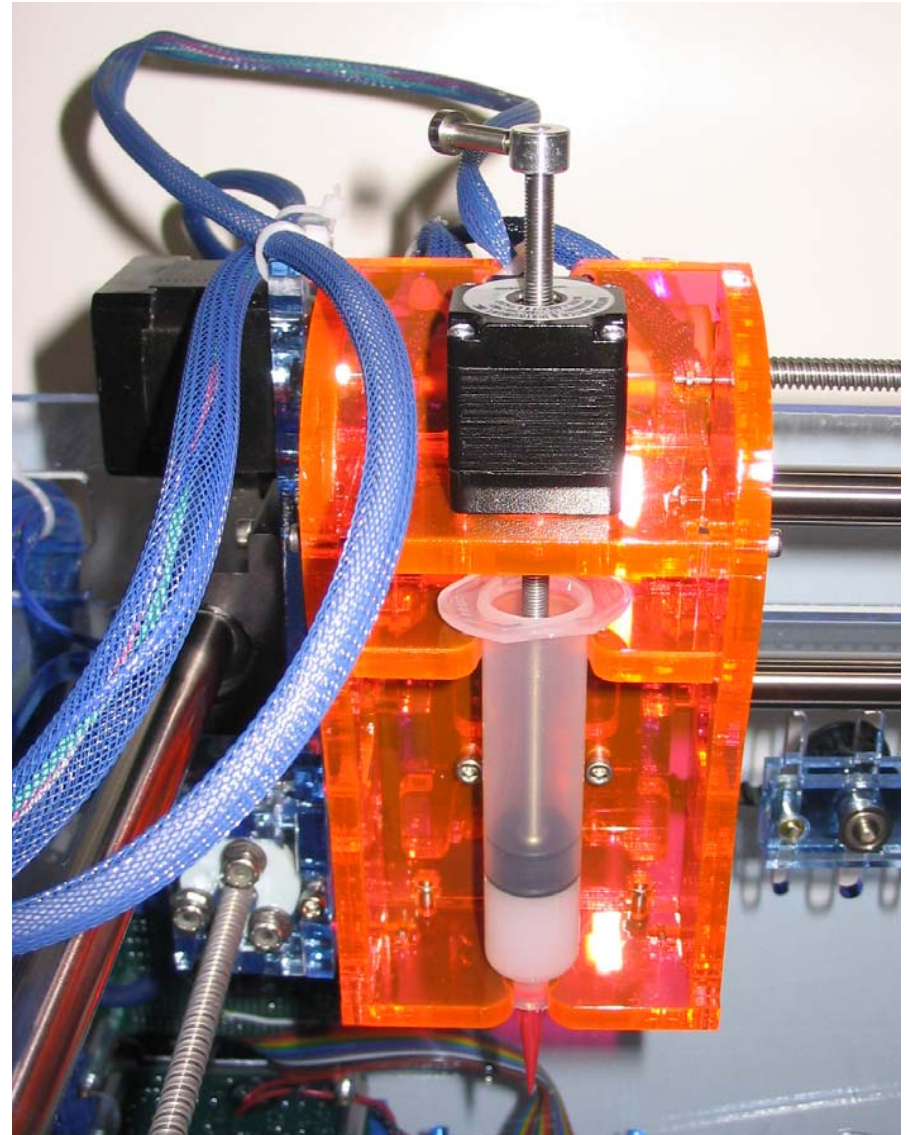
Technical Details - Mechanical

- XY Gantry, Z Table – Cartesian
 - Low XY inertia
 - Minimize object accel.
- 3 BP step motors with integrated lead screws (HSI Inc.)
 - Easy assembly
 - Expensive
- Timing belt couples X-slave axis
- Snap-together acrylic frame
 - Readily available
 - Brittle
- Sized for desktop
 - ~12 kg
 - ~0.5 m (L, W, H)
 - Mix of SI and Imp. units



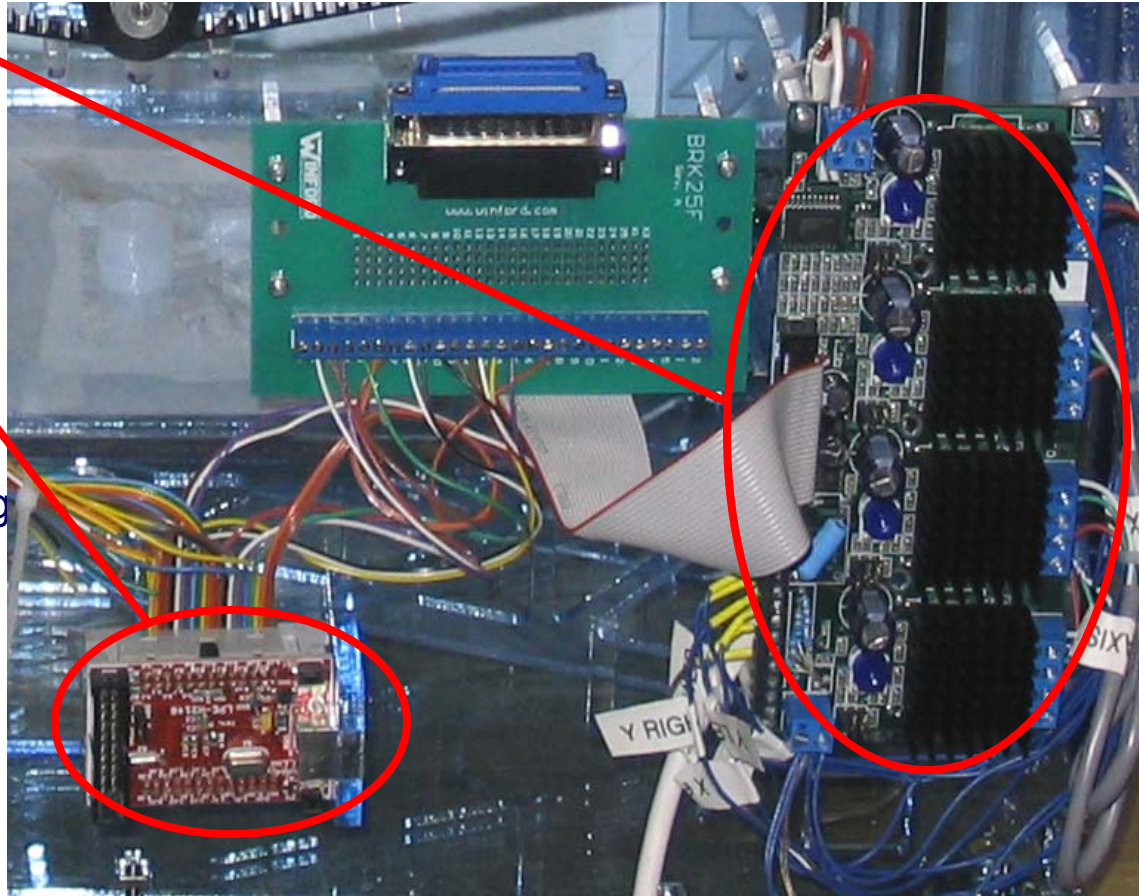
Technical Details – Deposition Tool

- Motorized syringe-pump(s)
 - HSI non-captive BP stepper
 - ~60PSI/~400kPa max
 - threads into nut in piston
- Plastic syringe barrels
- Quick “snap-in”
- Positive displacement reduces viscosity + friction sensitivity -> “Any material”
- Syringes too small for large jobs

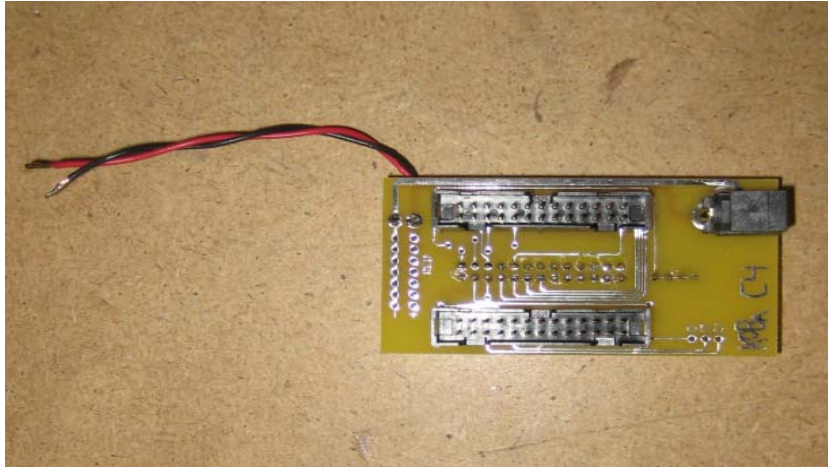


Technical Details - Electronics

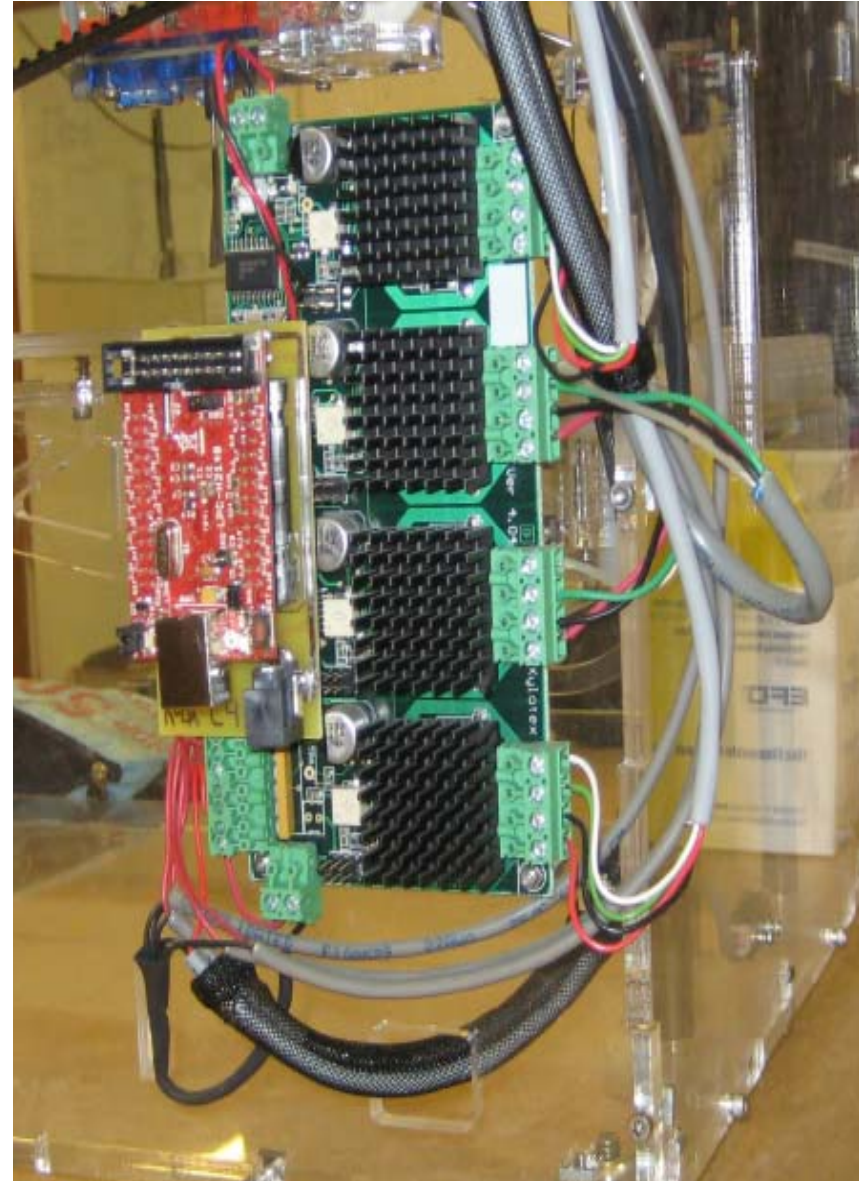
- Stepper amplifier
 - 4 axes
 - Bipolar
 - 1/8 stepping
 - 35V, 2.5A/ph max
- Microcontroller
 - ARM7 RISC
 - USB interface
 - A/D, D/A, SPI, etc.
 - JTAG programming
- Screw terminals
- Break-out board
- 24VDC / 30W global PS
- Strip & tin & screw assembly
- Wiring errors common



Electronics Improvements

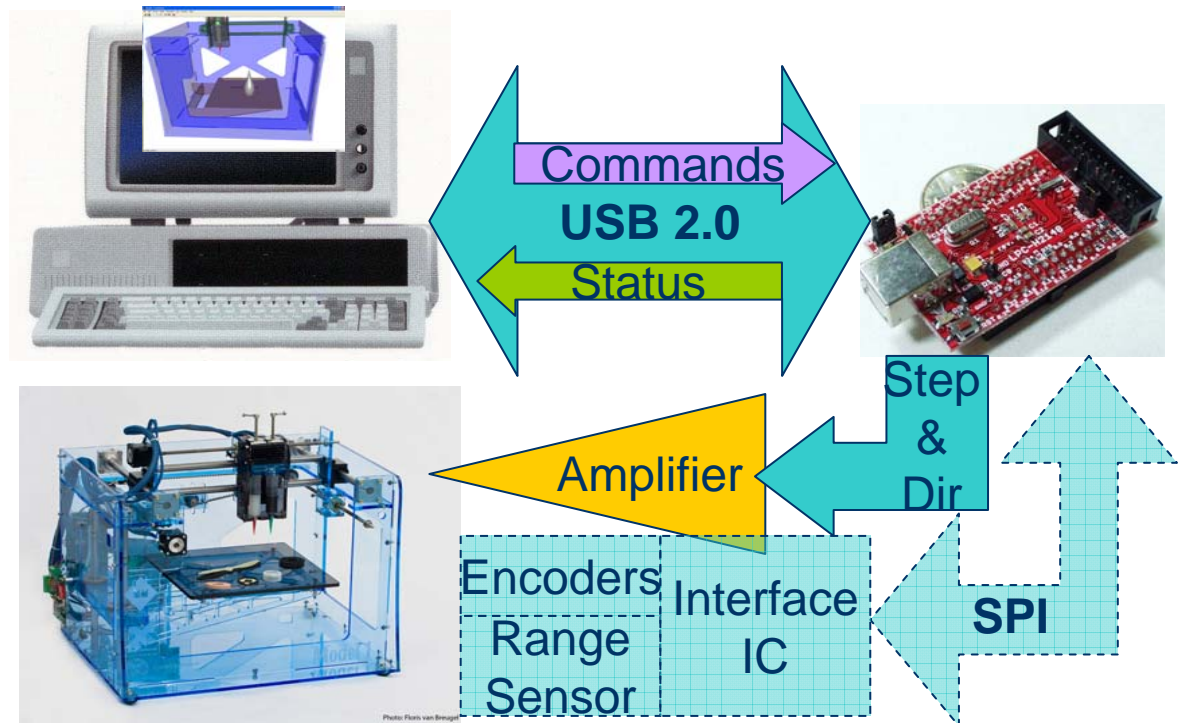


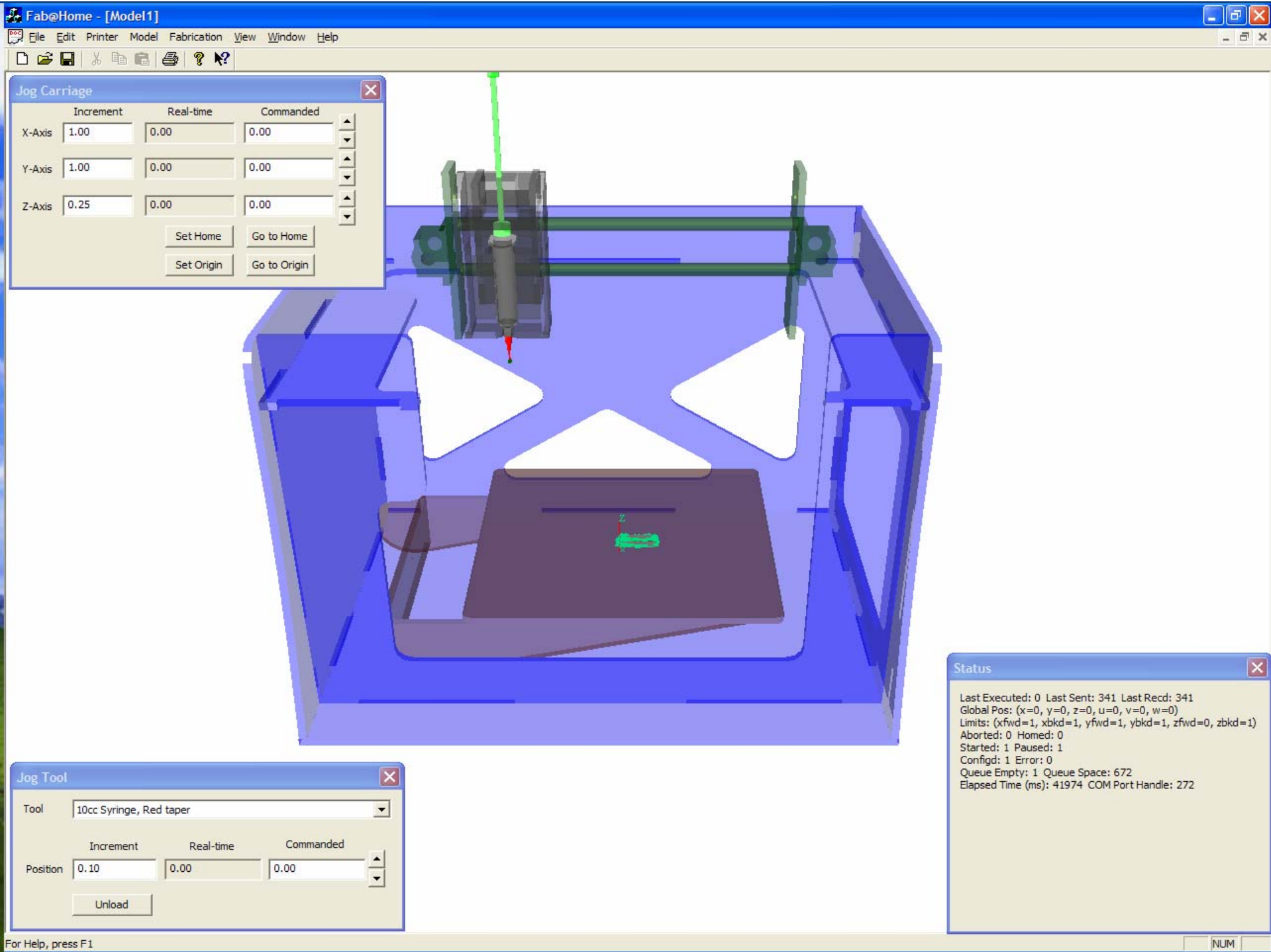
- Eliminate ribbon cables and breakout board
- Use power supply connector rather than cutting off
- Needs improved mechanical attachment
- USB noise sensitivity -> need electronics box
- Connectorize for 8P8C (LAN) cables?

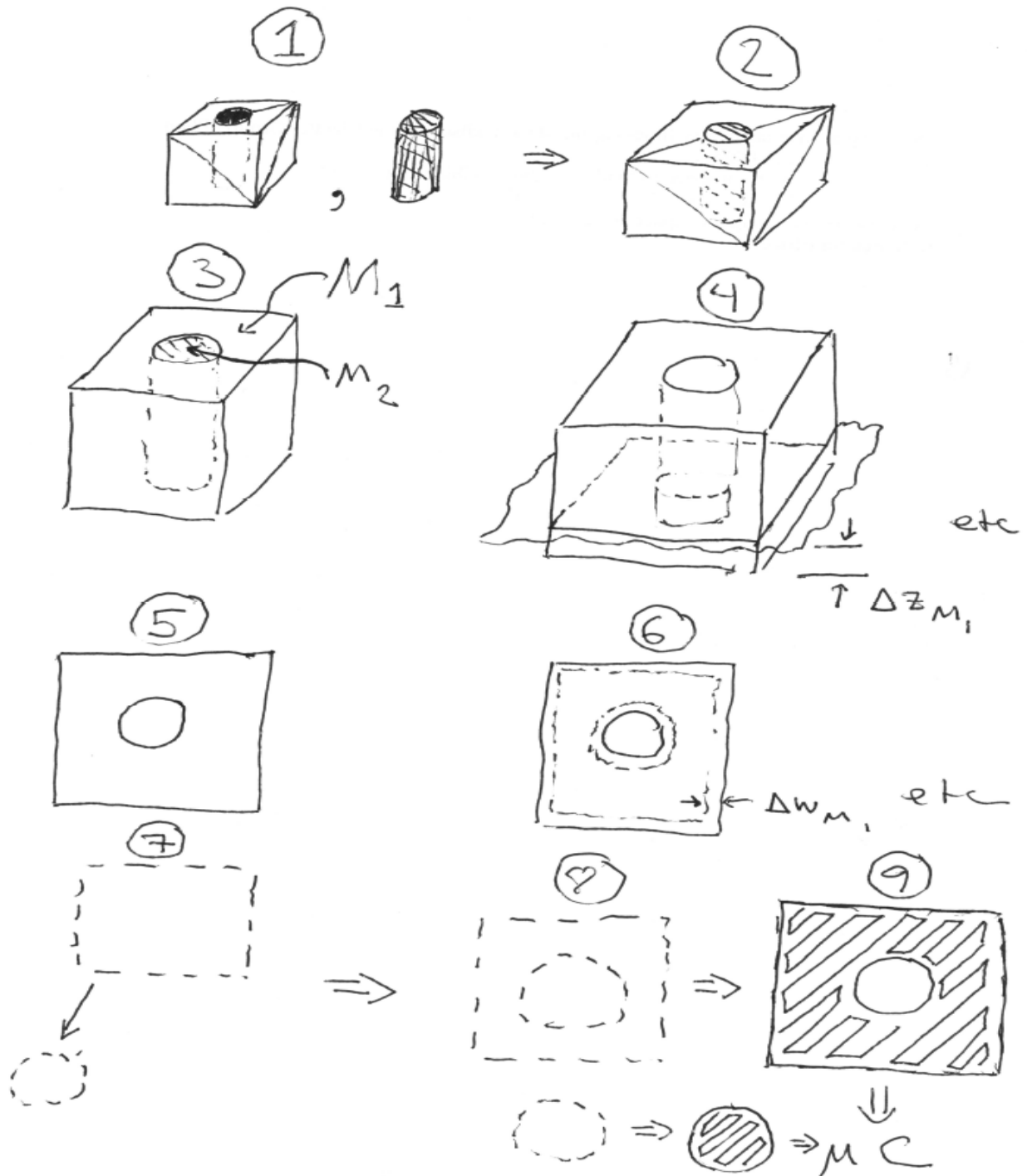


Control

- PC application
 - Win PC target
 - OpenGL GUI ~ WYSWYG
 - Intuitive operation and GUI
 - Import and process STLs
 - Multi-material assembly
- Firmware
 - Bidirectional packet USB2.0 comms
 - Status + commands
 - Queued and immediate commands
 - Queue ~ 700 6 dimensional path segments
 - Open loop steppers

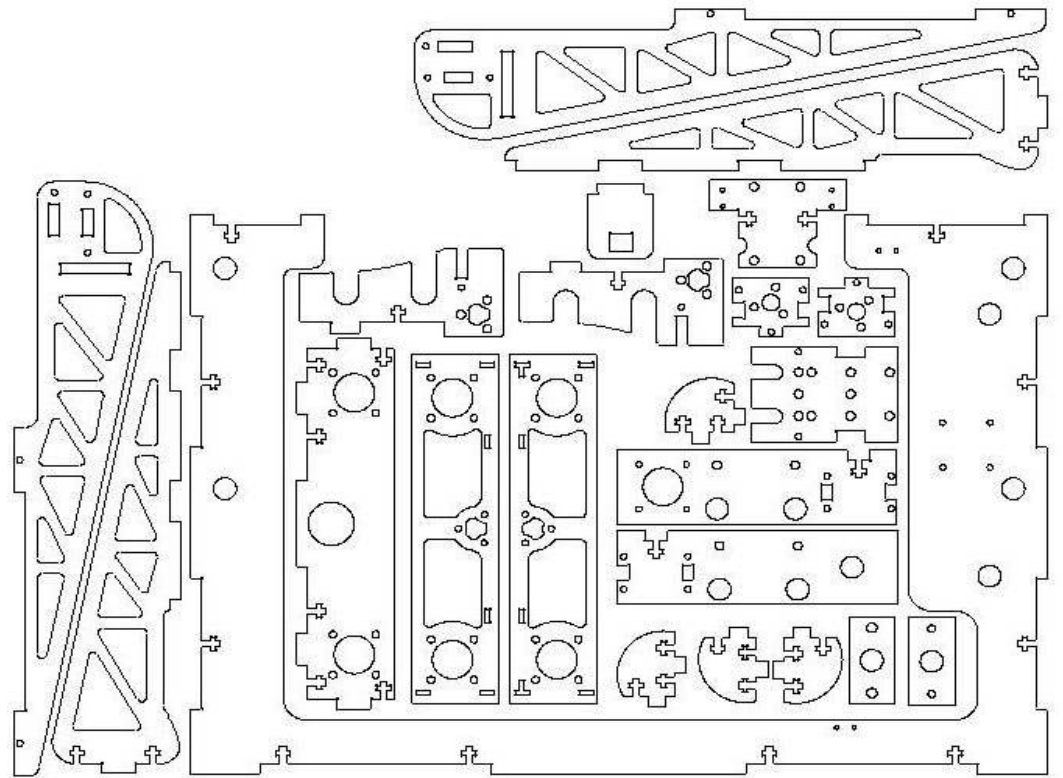
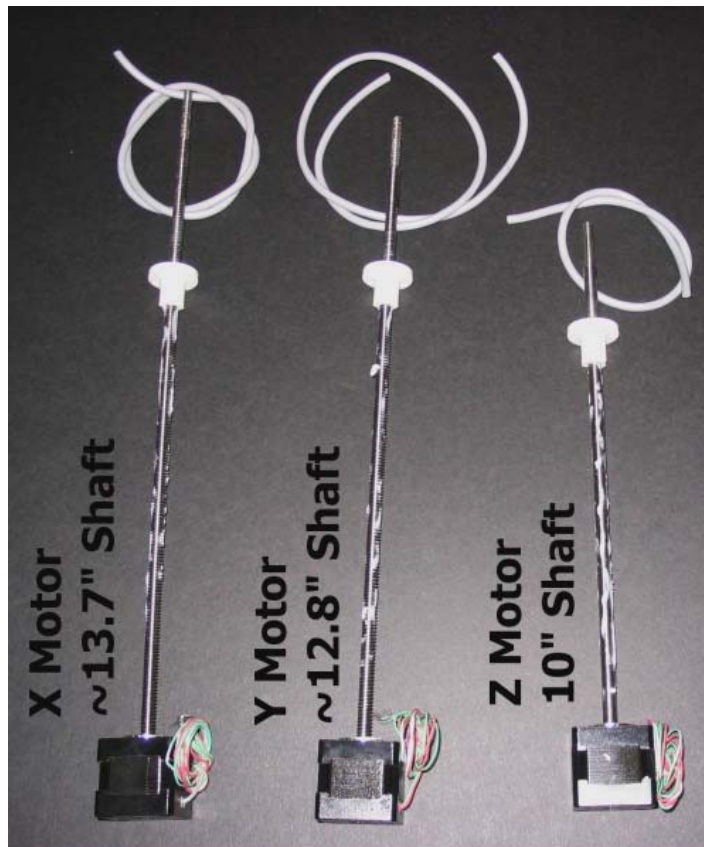






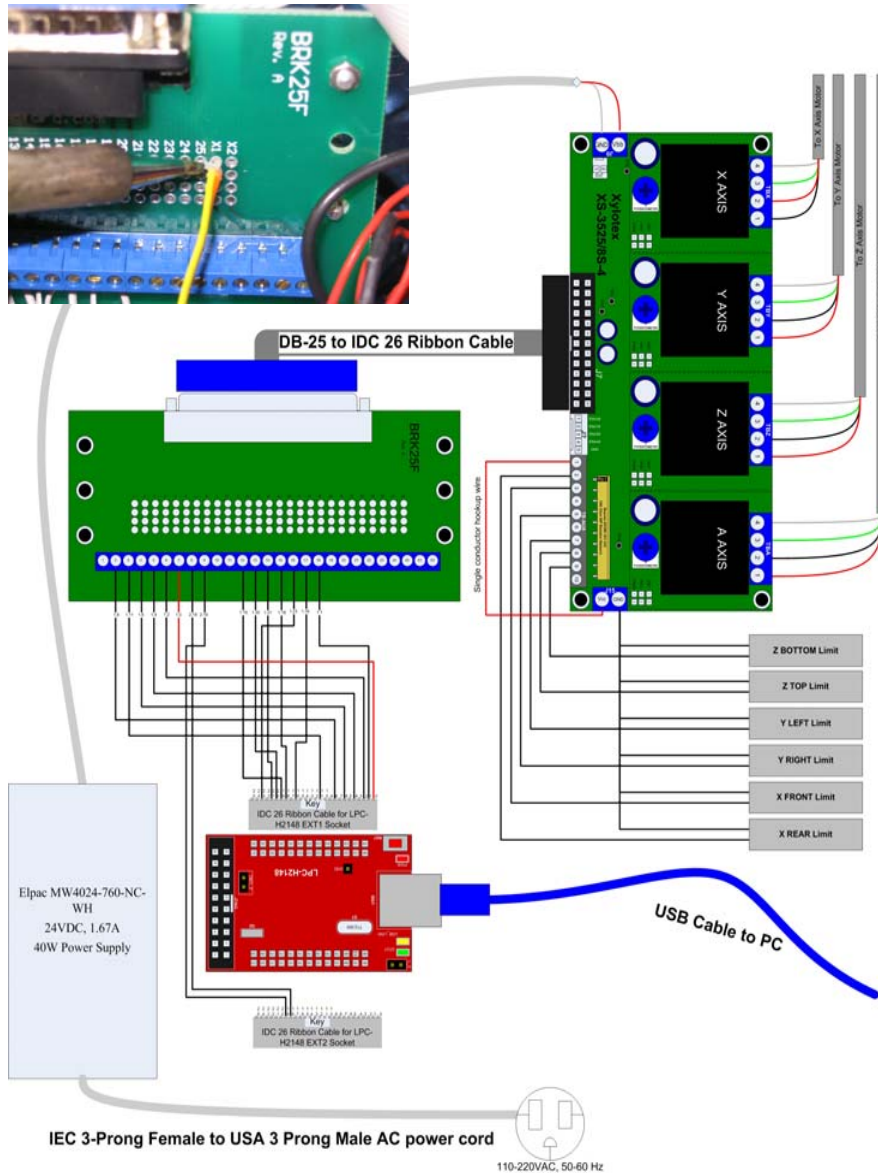
1. Import STL(s)
2. "Model"
3. Apply Materials
4. Slice STL(s) w. mat. params
5. "Layer" boundaries
6. Offset boundaries \rightarrow region edges
7. Nest edges in tree
8. "Region"
9. Create Region paths

Purchasing / Vendors

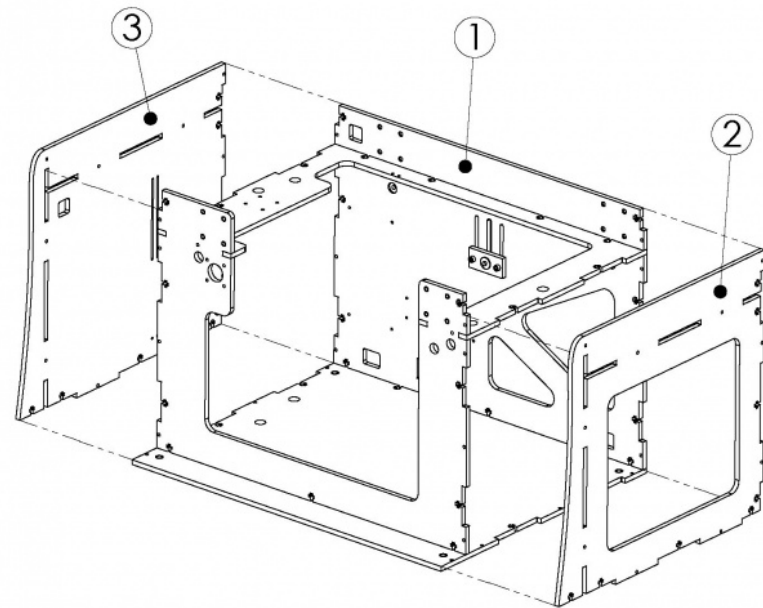


- Most parts off-the-shelf w. pre-filled web orders
- Motors semi-custom “kit” incl. prepared shafts and cables
- Complete kits and assembled machines comm. available

Example Assembly Instructions



Base Assembly Step 9



ITEM NO.	PART NUMBER	QTY.
1	Base-Step 8	1
2	Base Side Panel, Left, 0.236" THK Laser-cut Acryli	1
3	Base Side Panel, Right, 0.236" THK Laser-cut Acryli	1

Documentation and Collaboration



Fab@Home.org

Project explanation
HW Design docs
BOM/Vendors
Assy. Inst.
User manuals
FAQ/Contacts

FabAtHome.org:

- Documentation
- Downloads
- Images & Video

SourceForge.net:

- Collaborative Software Development

GoogleGroups:

- Discussion forum for Users

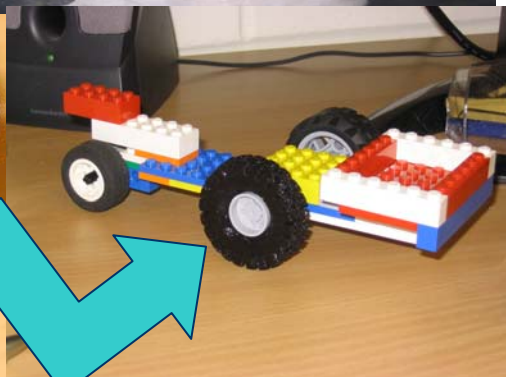
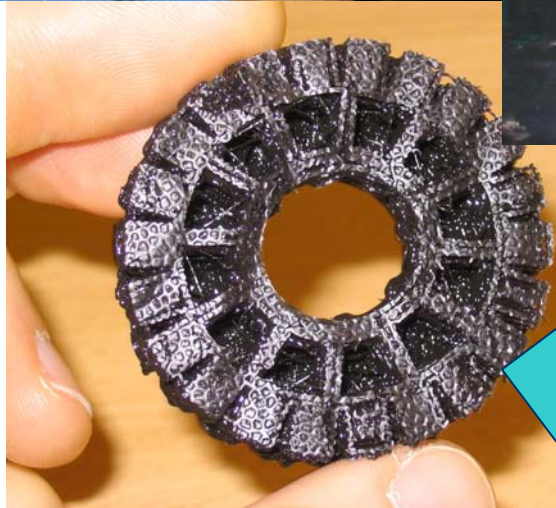
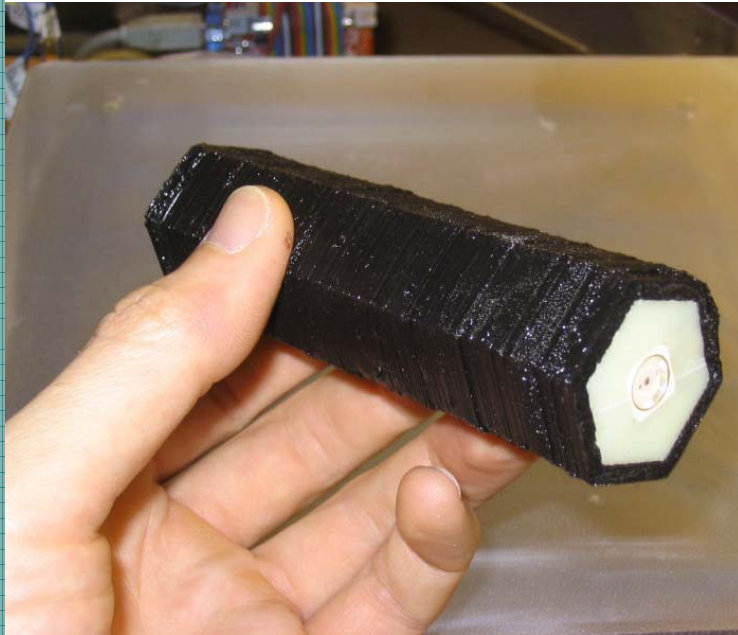
SourceForge

App. source
Firmware source
Driver source
Bug tracking
Feature reqs.
Developer Forums

GoogleGroup

Group purchasing
Brainstorming
User-user Q/A

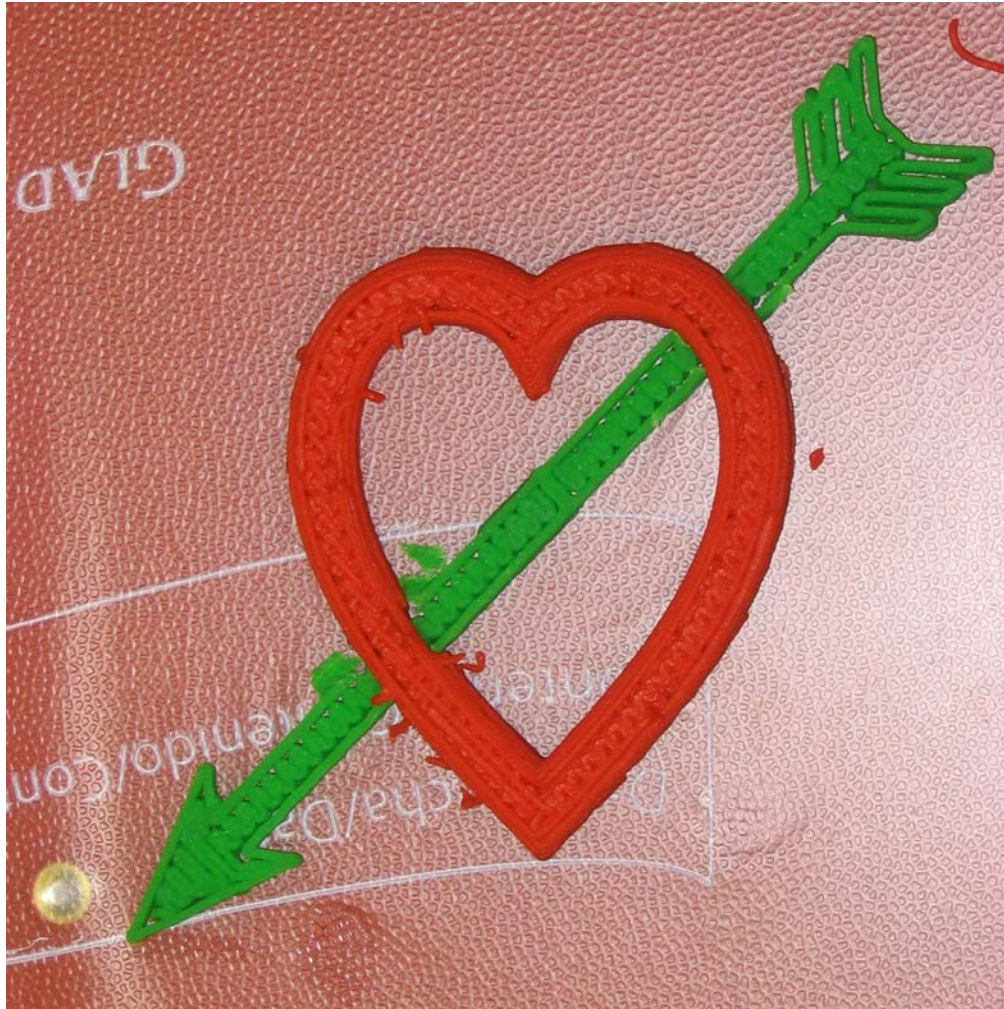
Rubber and Epoxy Products



Clockwise from above:

- LED Flashlight
- Epoxy Propeller
- Watchband with embedded watch
- Silicone bottle
- Lego truck sporting replica Lego tire

Food Products

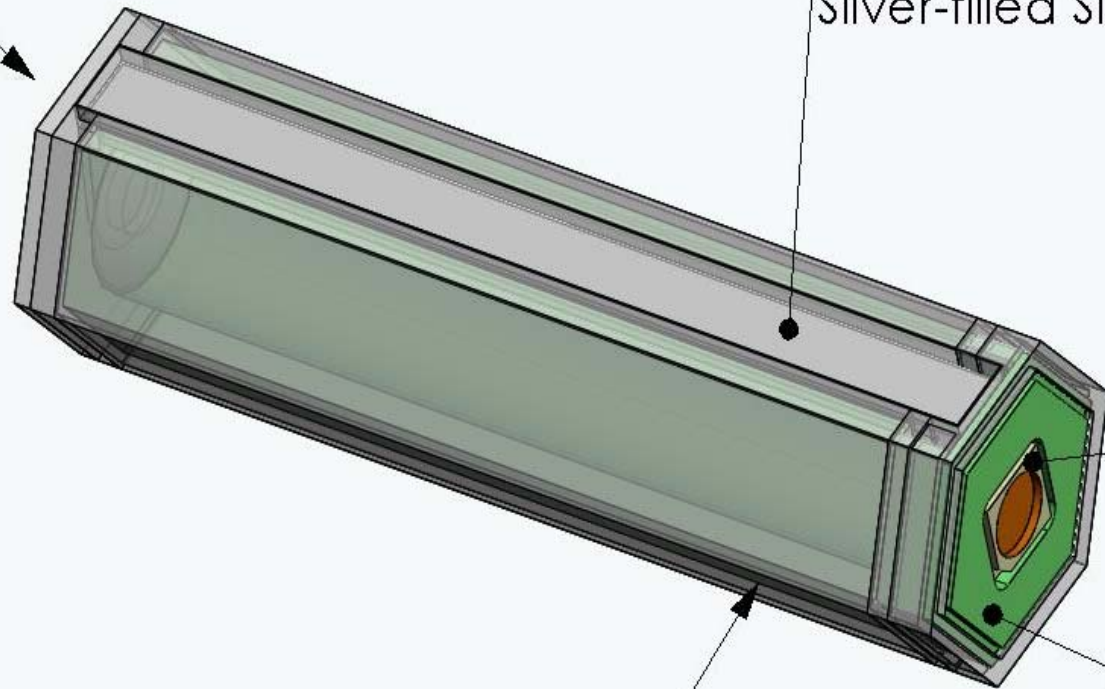


Frosting Cake Decoration, D. Periard,
Cornell Univ., NY, USA



Printed Chocolate, N. Schaal, Manual
H.S., KY, USA

End-cap
and
Switch



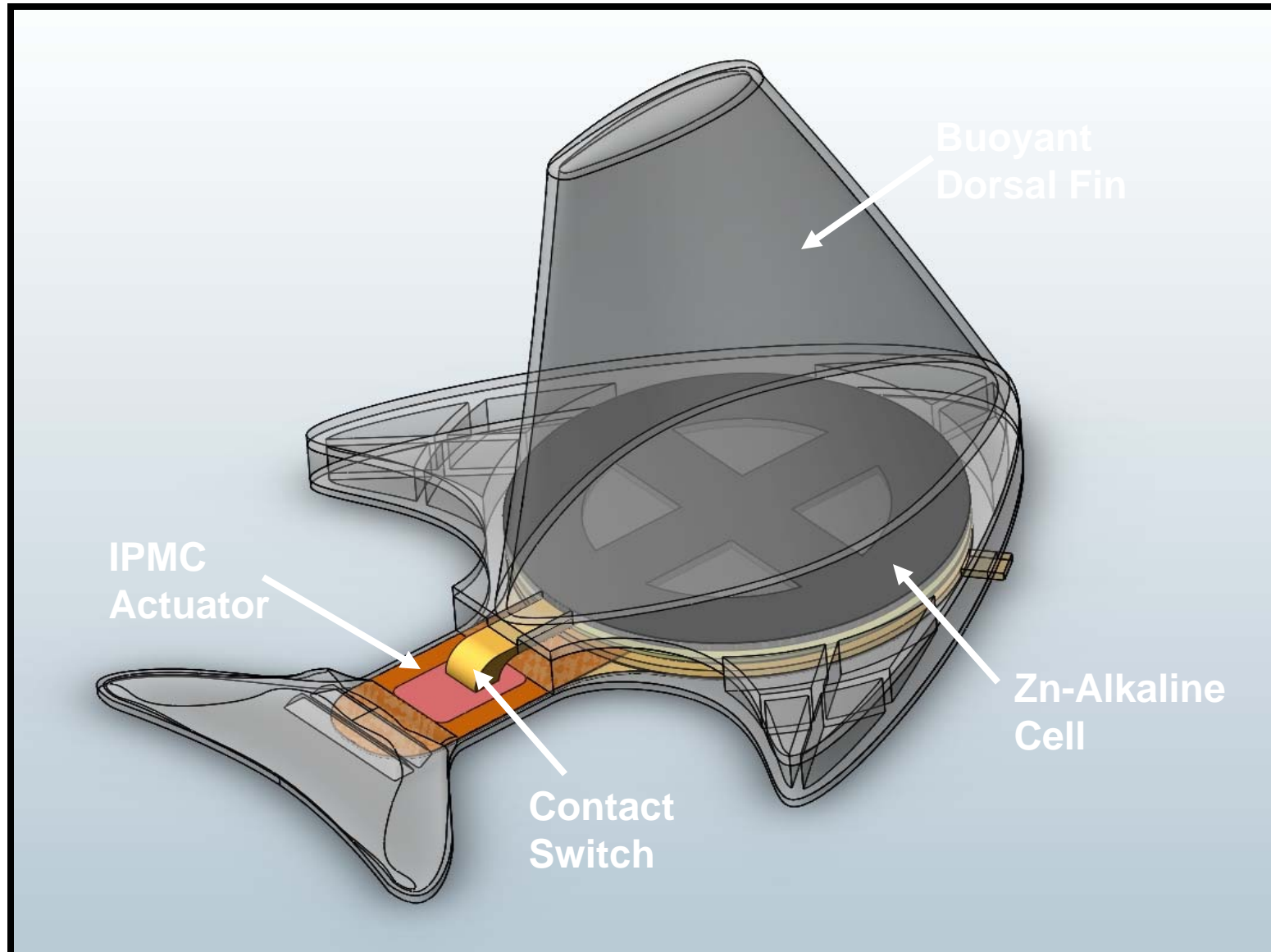
Silver-filled Silicone Circuit

LED

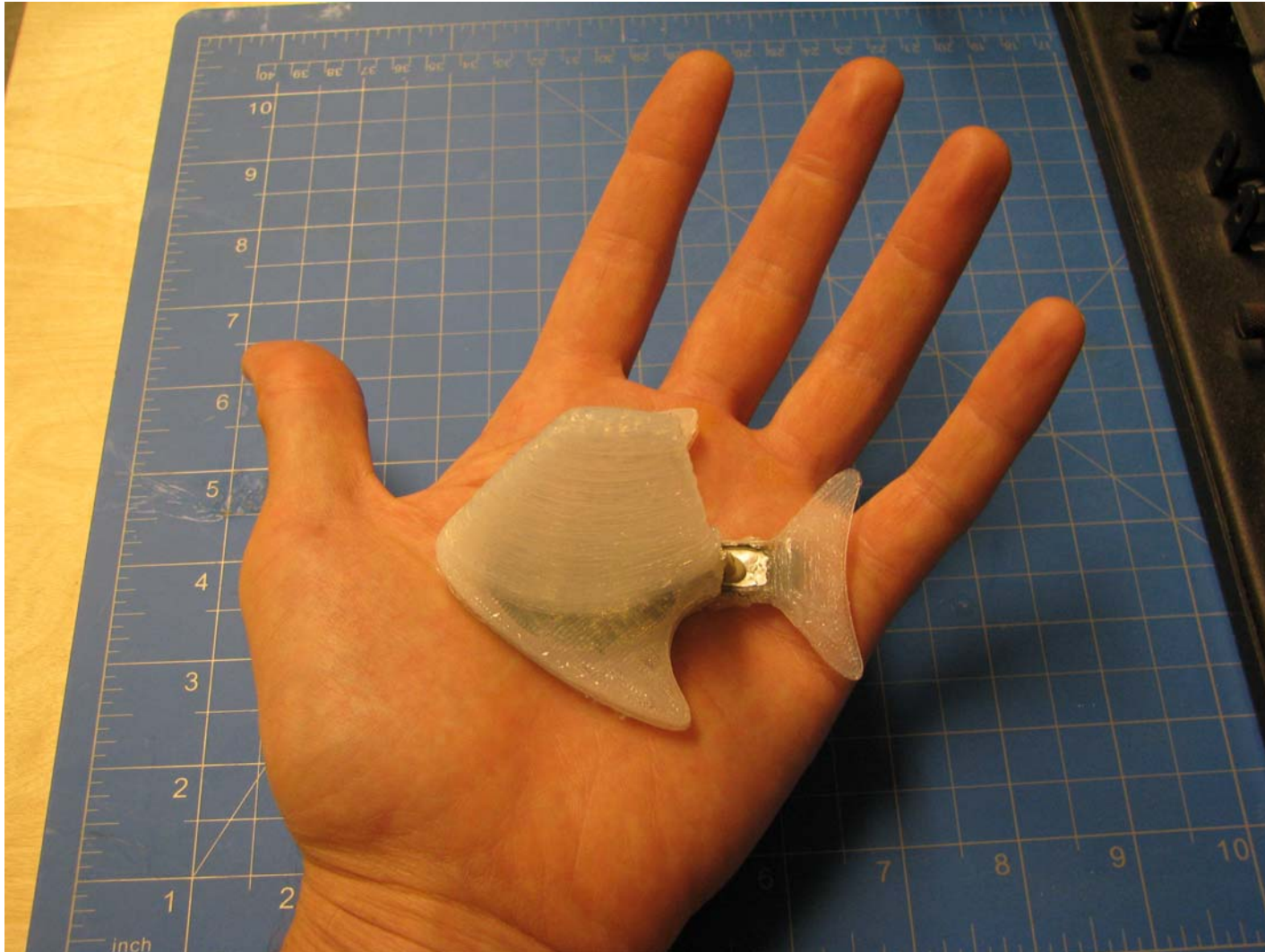
Epoxy Front Plate

Silicone Skin

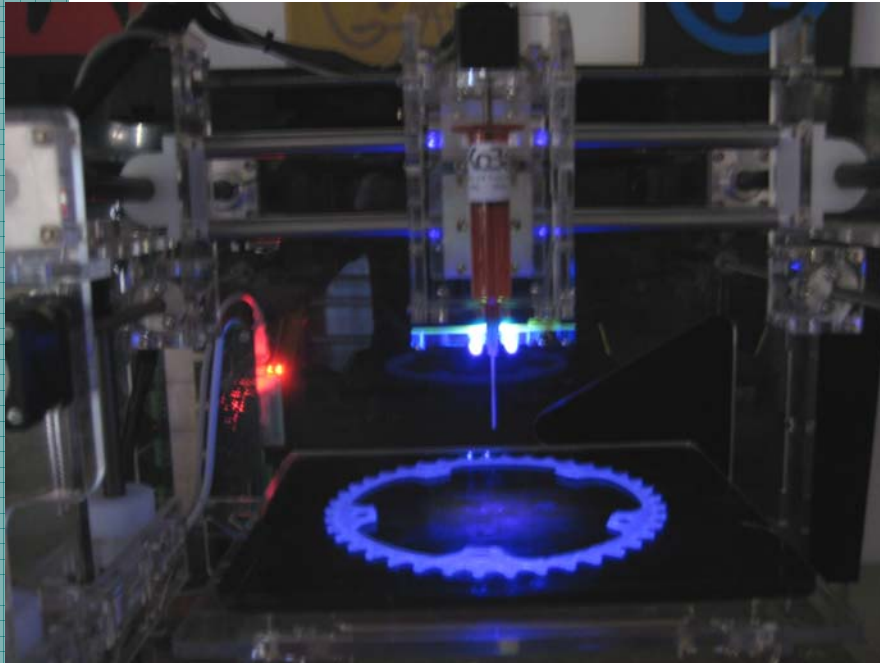
Printed "Fish Robot" Concept



Printed “Fish Robot” Prototype

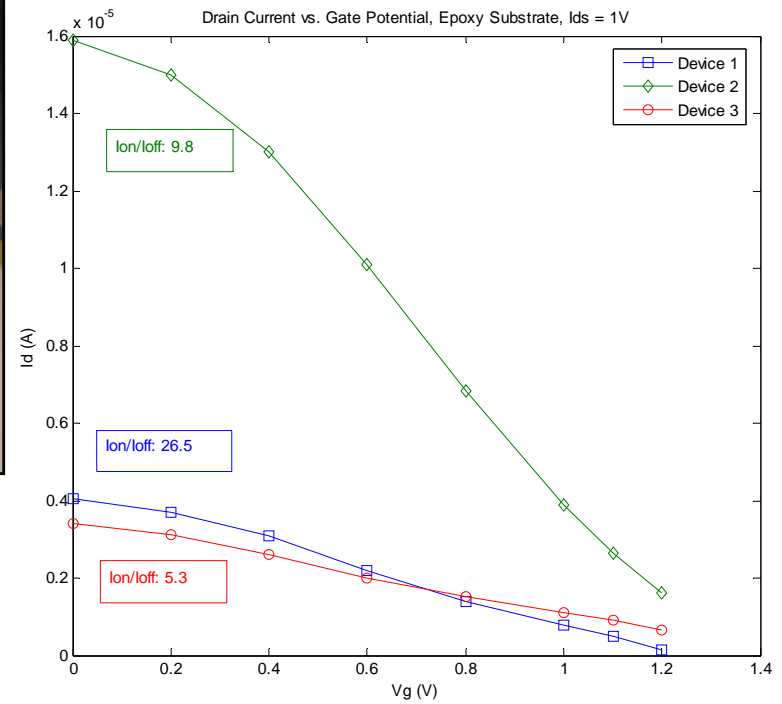
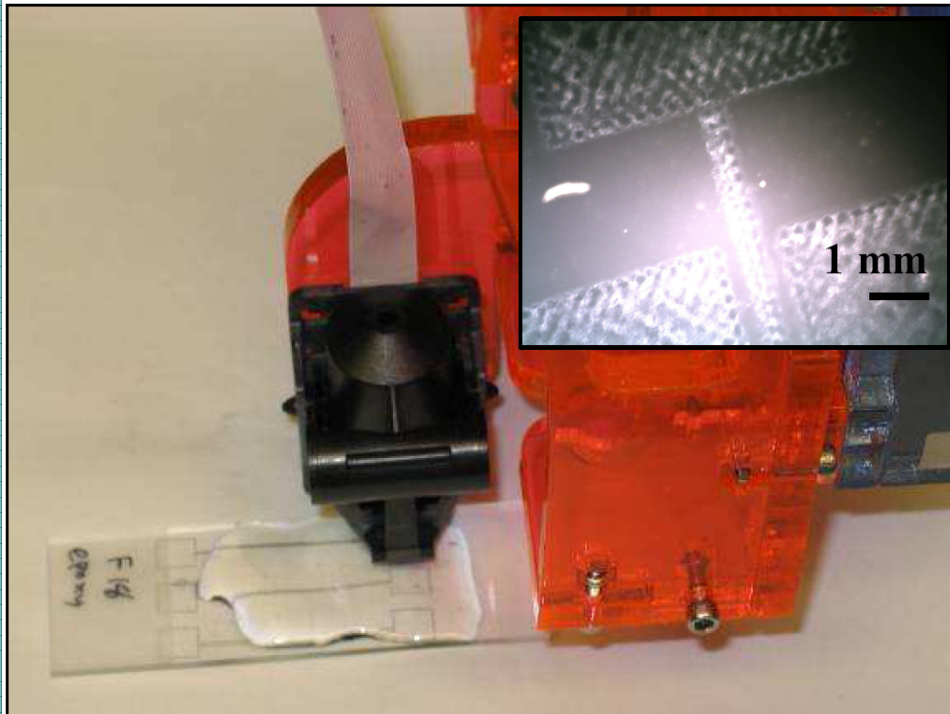


New Process: UV-cure Epoxy

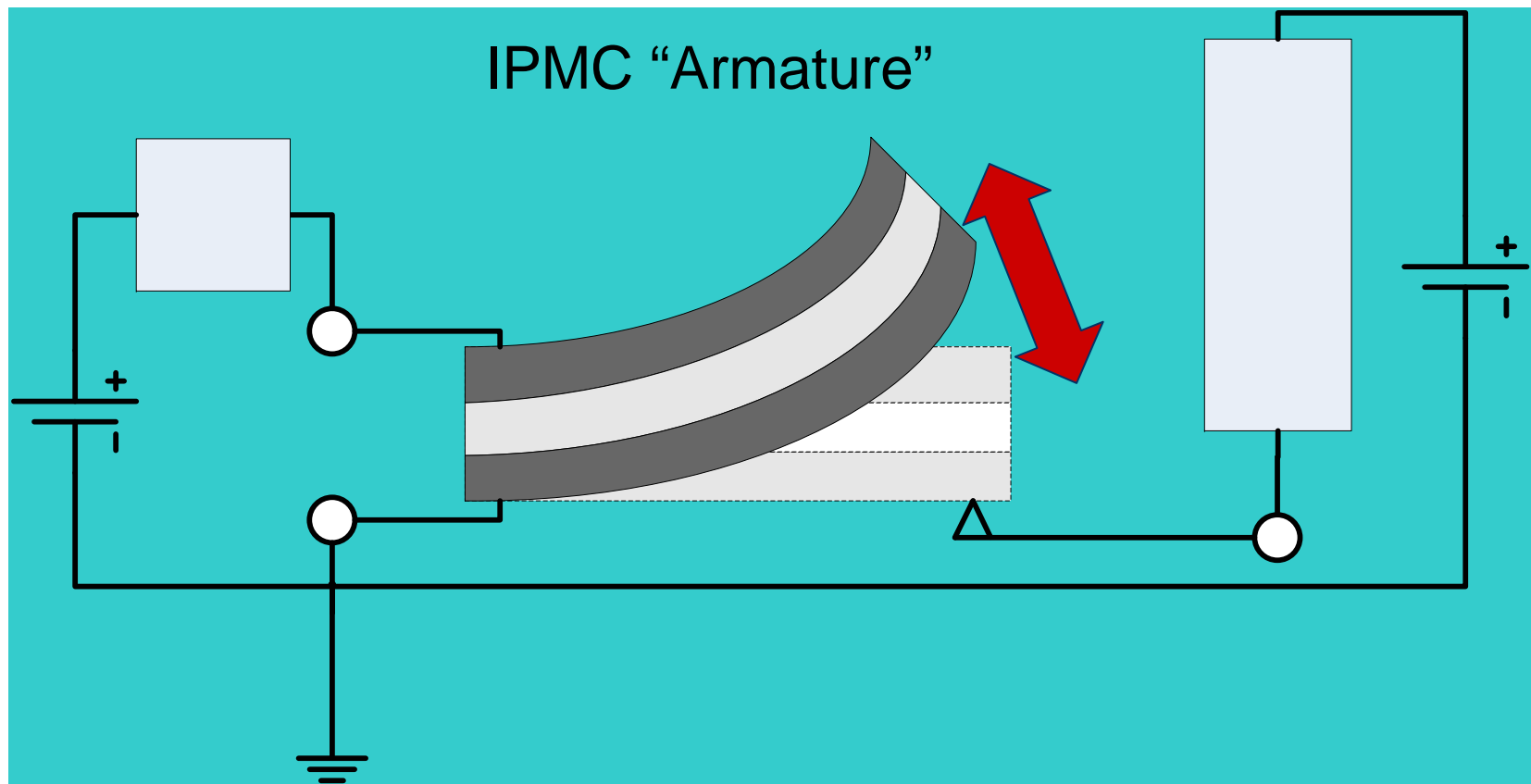


Work by Koba Industries, Albuquerque NM USA

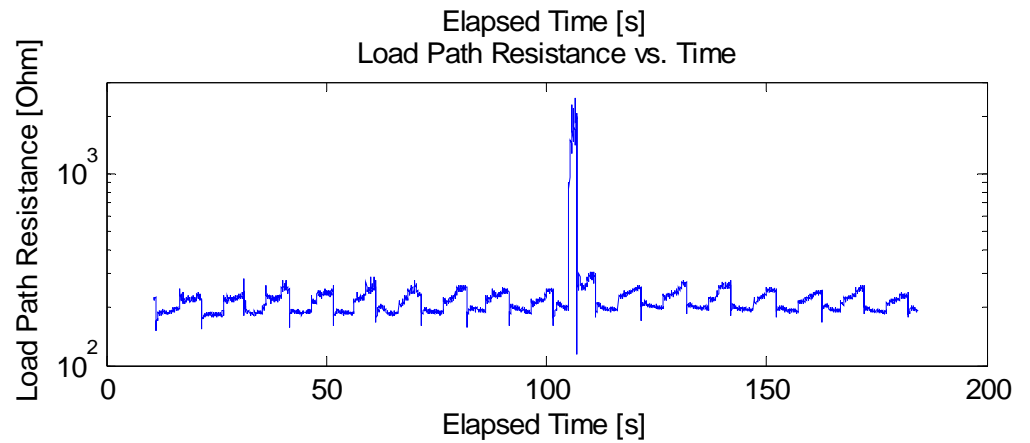
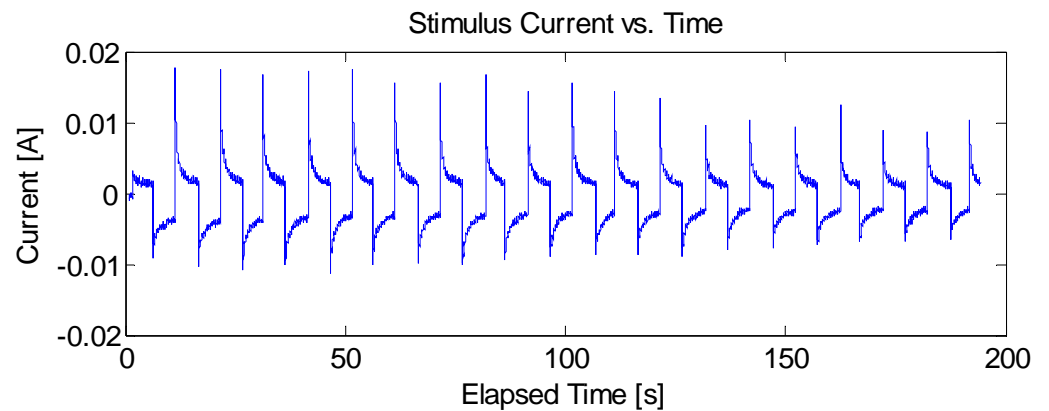
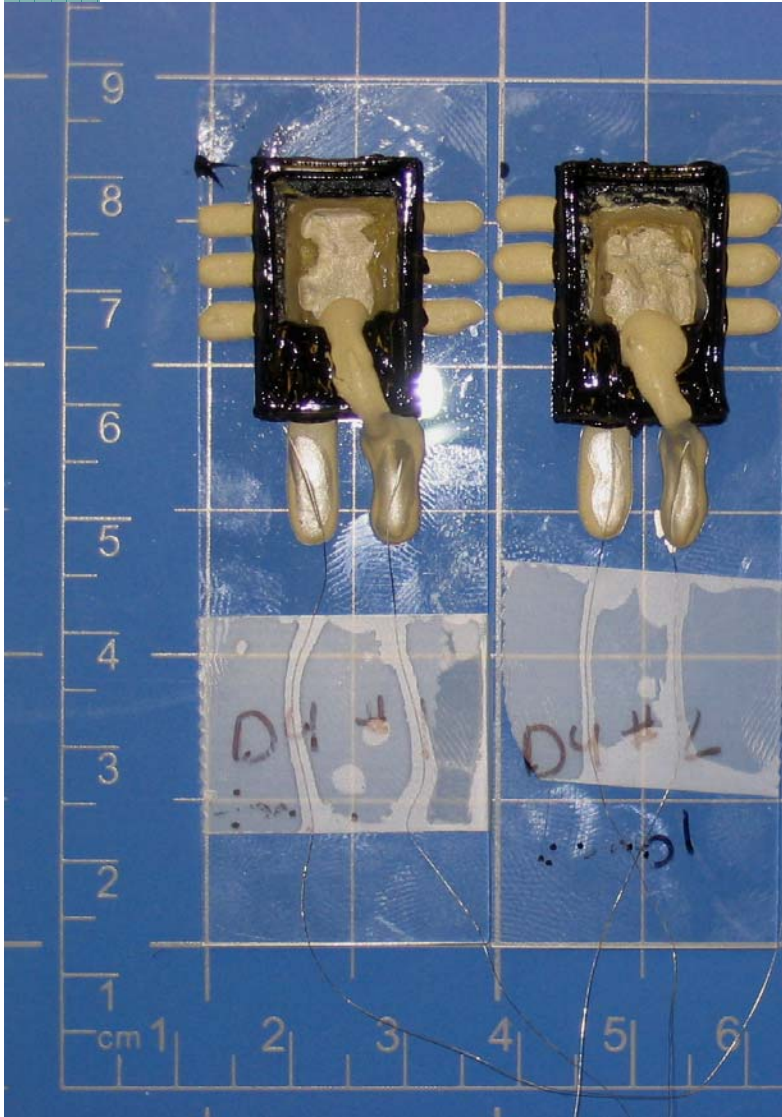
Organic Transistors



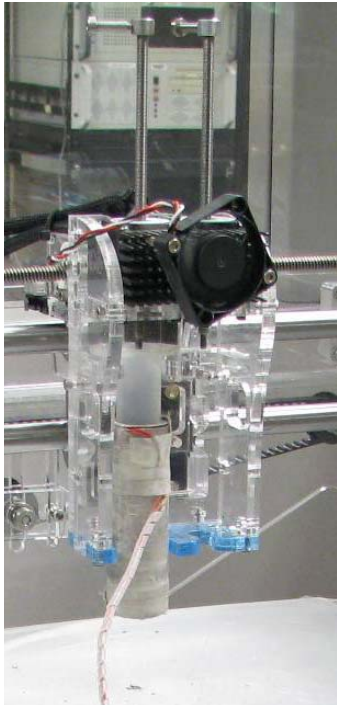
IPMC Relay



IPMC Relay Prototypes



New Process: Sintered Stainless



- 17-4 PH Stainless Steel powder, 12 μ m
- Polysaccharide binder; aqueous
- Deposited at 85° C via heated syringe
- Sintered 8h @ 1350°C in 6% H - 94% Ar
- 35% UTS of bulk 17-4 PH
- 17% linear shrinkage

Work by Maxim Lobovsky, Cornell University



Future?

- Model 2
- Modular Personal Fabrication Architecture & Standards